

# Advanced Tutorial on Coevolution

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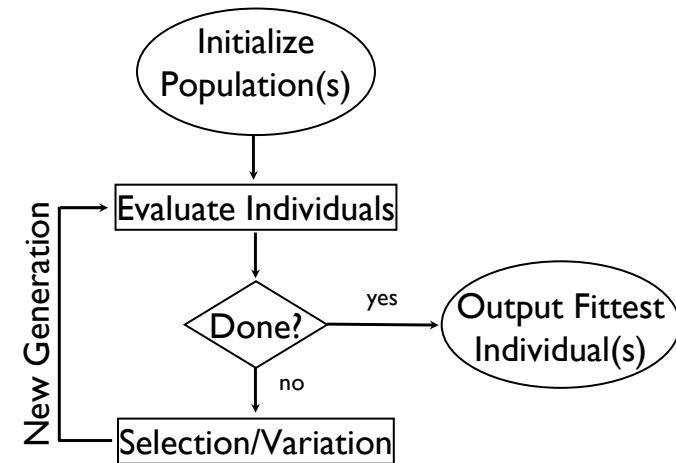
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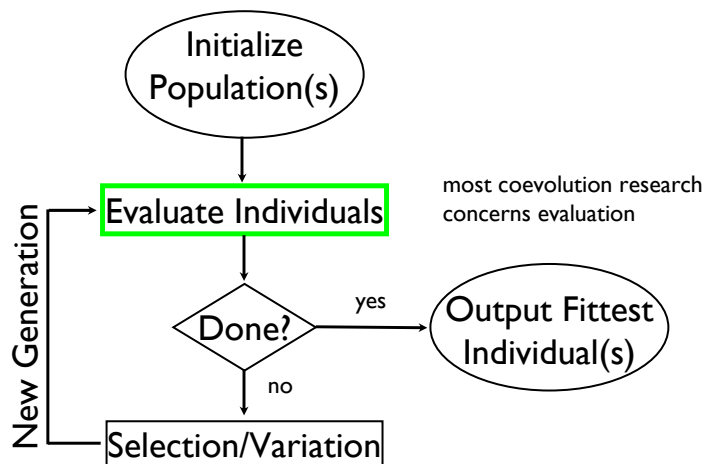
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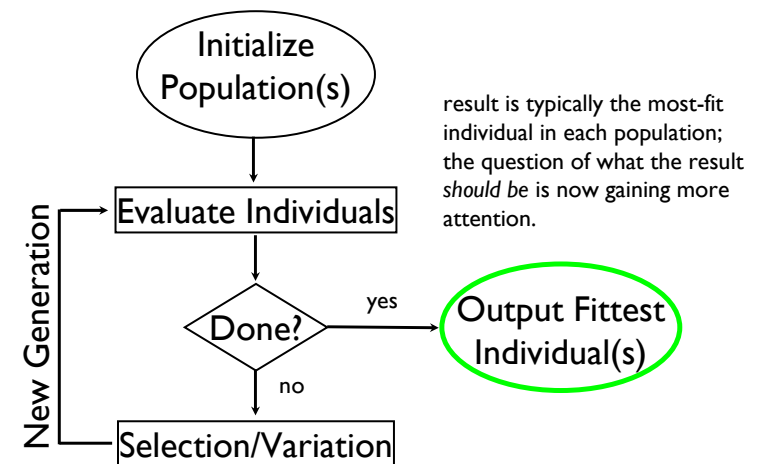
## Conventional Coevolution



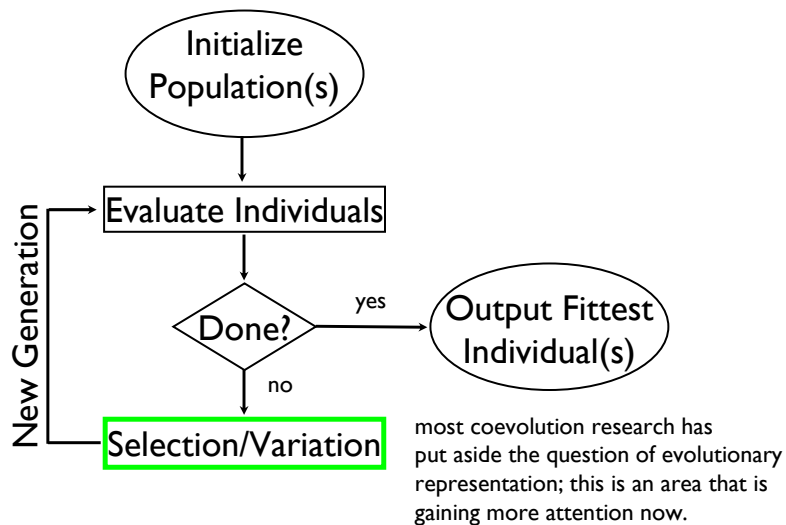
## Conventional Coevolution



## Conventional Coevolution



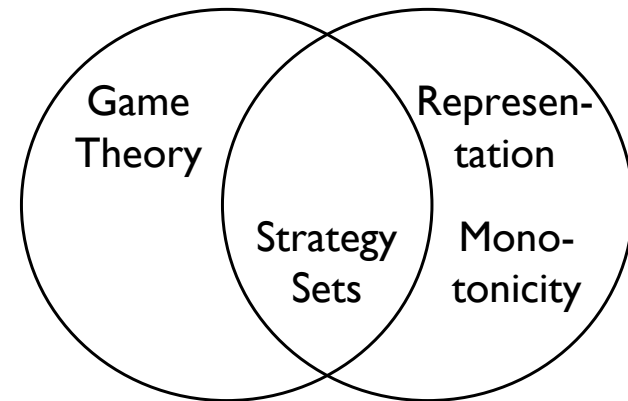
## Conventional Coevolution



## Main Themes

Interaction

Elaboration



## Interaction

- To evaluate an individual in coevolution, we must have it interact with others
- The outcome of evaluation is contingent upon whom the individual interacts with
- The individual may appear good in one context and poor in another context
- This context sensitivity is game theoretic in nature
- Solutions may be sets of individuals

## Elaboration

- We want the evolving individuals to improve over evolutionary time
- Coevolutionary “arms race” is an example
- Improvement can be viewed as an accumulation of competences, or elaboration
- We will discuss different forms of elaboration

## Main Topics

- Game theory
  - game, strategies, payoffs
  - solution concepts: implementation
- Strategy sets
  - Mixtures, Pareto front, archives, ...
- Representation
- Monotonic improvement over time

## Motivation: Coevolutionary Pathologies

- Cycling: algorithm revisits a portion of state-space periodically—no progress
- Disengagement: loss of fitness gradient
- Overspecialization: lack of elaboration
- Forgetting: loss of potentially useful traits
- Relative overgeneralization: favoring of versatile components over those of optimal solution

## Game Theory

- Mathematics of strategic reasoning  
[Fudenberg & Tirole 1998]
- If we have a number of interacting agents...
  - How will they behave; what will be outcome?
  - If we interact, how should we behave?
- Provides descriptive predictions of how players will behave
- Provides prescriptive (normative) instructions on how to behave

## Game Theory

- Provides predictions and instructions about behavior
- Assumes all agents are rational, selfish
- Nash equilibrium [Nash 1951]
  - A configuration of strategic choices such that no player has incentive to deviate unilaterally from its current strategy
  - All finite games have at least one Nash equilibrium

# Game Theory: Components

- Game specifies for each player...
  - strategies that are available
  - outcomes that result for each strategy when interacting with other players' strategies
- Solution concept
  - formal specification of what configuration of players' behaviors (strategies) constitutes a solution to the game

# Rock Paper Scissors

		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	0	-1	1
	Paper	1	0	-1
	Scissors	-1	1	0

# Rock Paper Scissors

		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	0	-1	1
	Paper	1	0	-1
	Scissors	-1	1	0

- Pure strategies: rock, paper, scissors
- Mixed strategy: any probability distribution over pure strategies

# Rock Paper Scissors

		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	0	-1	1
	Paper	1	0	-1
	Scissors	-1	1	0

- Payoffs (outcomes) for all possible pure-strategy interactions
- For mixed strategies, we calculated expected payoffs based on probability distributions used

## Rock Paper Scissors

		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	0	-1	1
	Paper	1	0	-1
	Scissors	-1	1	0

- Rock > Scissors > Paper > Rock
- No pure strategy is universally best
- Solving this game requires a set of strategies

## Rock Paper Scissors

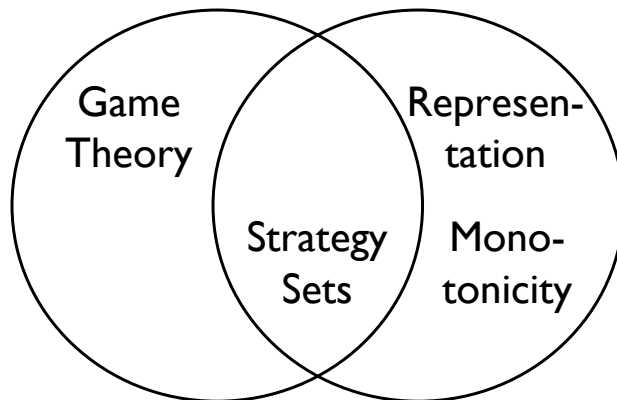
		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	0	-1	1
	Paper	1	0	-1
	Scissors	-1	1	0

- Nash equilibrium strategy is mixed
  - R, P, S each played with probability = 1/3
  - expected payoff of Nash player is zero, regardless of what other player does
  - expected payoff of other player is also zero, regardless of what it does

## Main Themes

Interaction

Elaboration



## Interaction and Elaboration

- From the outcomes of pure-strategy interaction...
  - we find that no single pure strategy provides all needed competences
- The Nash mixed-strategy...
  - is a set of pure strategies...
  - and represents an elaboration of pure-strategies

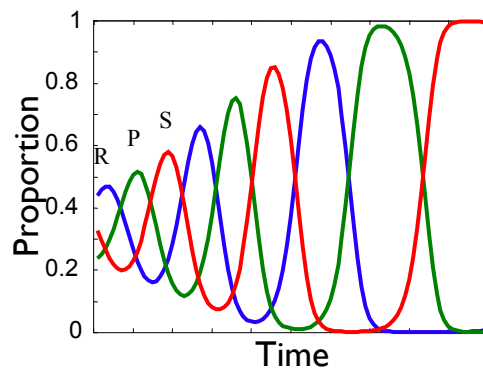
## Solution Concept

- ❑ Specifies properties of a solution
  - (not the solution itself)
- ❑ But must be implemented in search algorithm
- ❑ Incorrect implementation of solution concept will cause search algorithm to diverge from desired solution properties

## Solution Concept

- ❑ Examples where algorithm fails to implement Nash equilibrium in a game
  - Proportional selection and Rock-Paper-Scissors: mixed Nash equilibrium? [Hofbauer & Sigmund 1998]
  - Alternative selection methods and Hawk-Dove game [Ficici et al. 2000, 2005]
  - Diversity maintenance methods and Hawk-Dove game [Ficici 2001]

### Rock-Paper-Scissors



- ❑ Under fitness-proportional selection...
  - Nash equilibrium represented as polymorphic population of pure-strategists is unstable
  - Nash equilibrium also unstable for mixed strategists
- ❑ Nash concept not properly implemented here

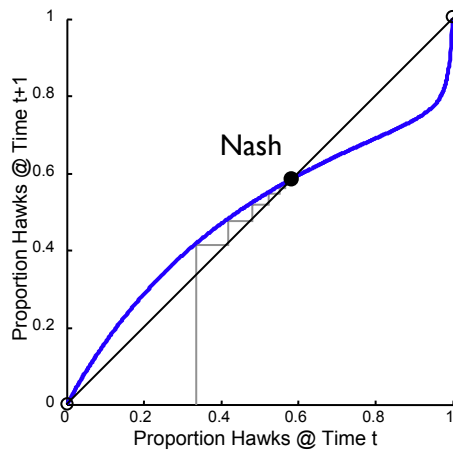
### Hawk-Dove Game

[Maynard Smith 1982]

	Hawk	Dove
Hawk	-25	50
Dove	0	15

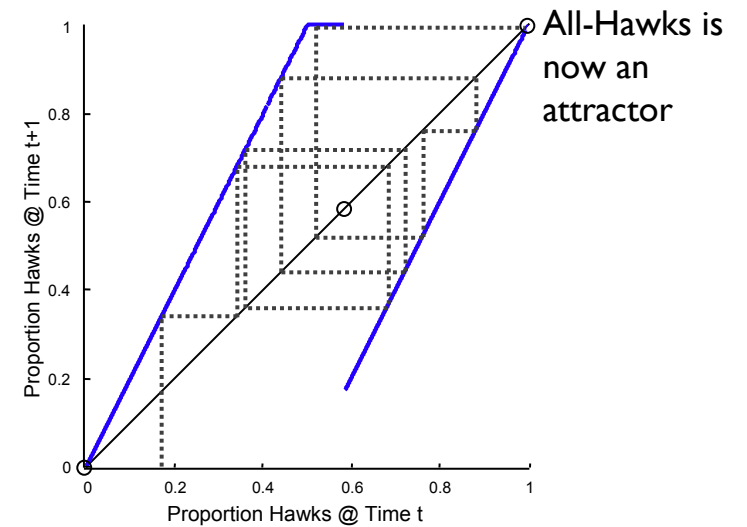
- ❑ Nash equilibrium strategy for these payoffs:
  - 7/12 Hawk, 5/12 Dove
  - probability distribution for a mixed strategy...
  - OR proportions for polymorphic population of pure-strategists

## Proportional Selection

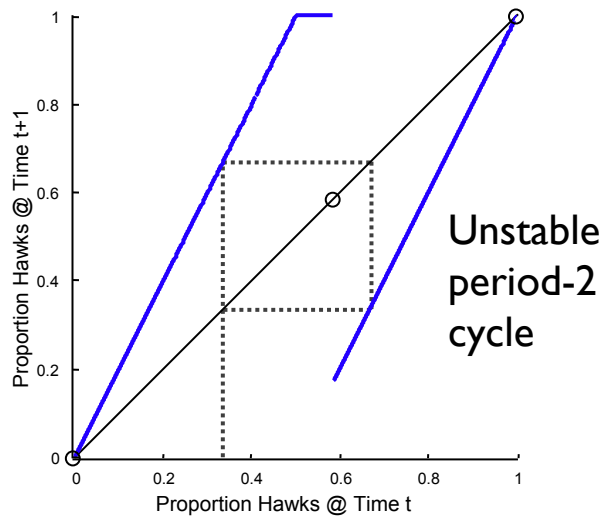


Nash equilibrium is dynamical attractor

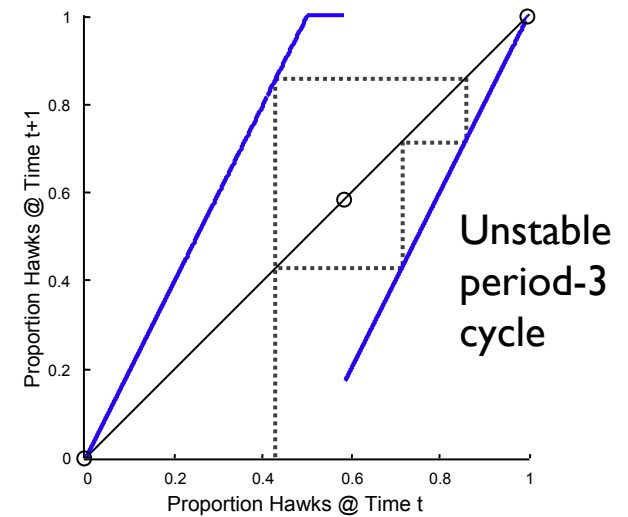
## Truncation Selection



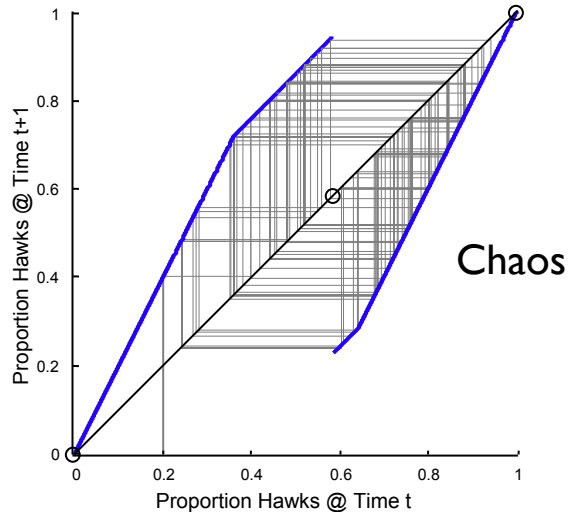
## Truncation Selection



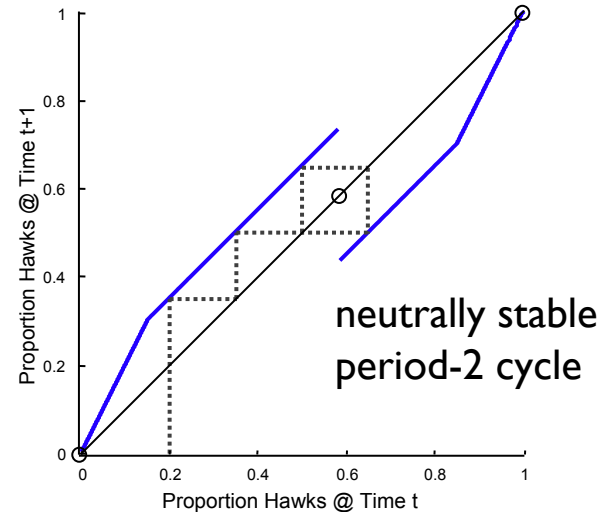
## Truncation Selection



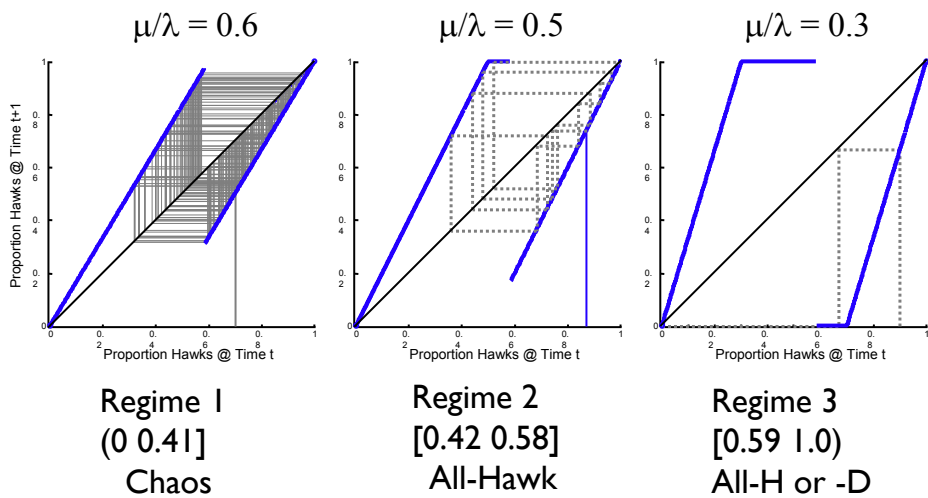
## Truncation Selection



## Truncation Selection

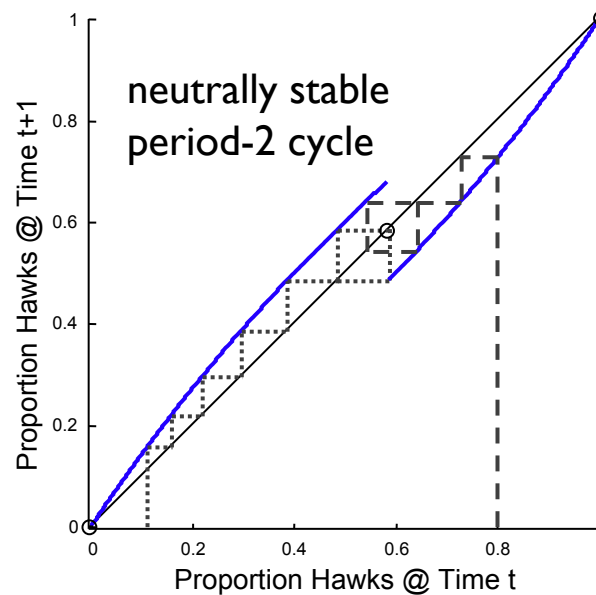


## $(\mu, \lambda)$ -ES Selection



*selection pressure increase* →

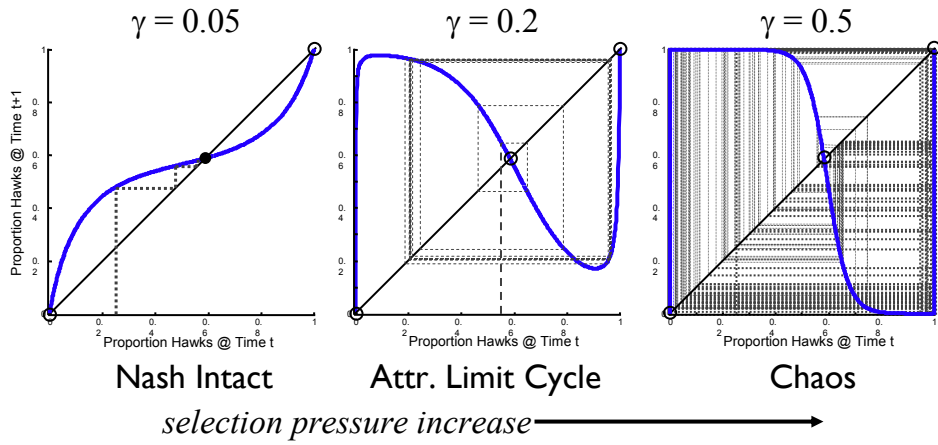
## Rank Selection



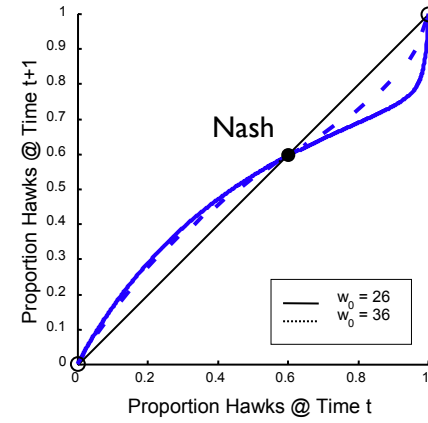


# Boltzman Selection

$$f_{\text{Boltz}} = e^{\gamma f}$$

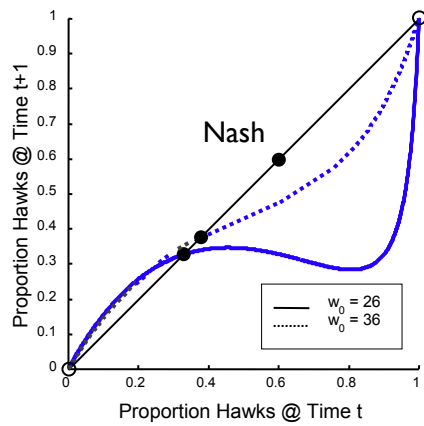


# Proportional Selection



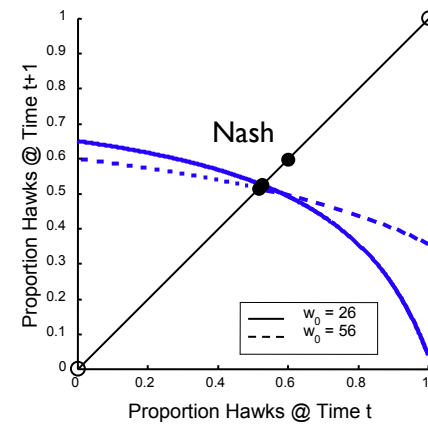
# Competitive Fitness Sharing

[Rosin 1997]



# Similarity-Based Fitness Sharing

[Goldberg 1989]



## Discussion

- We use different selection methods and diversity-maintenance methods to improve search for a particular domain
- Evolving population expected to both:
  - contain sufficient genetic diversity for search
  - represent solution to search task (may be a polymorphism)
- These tasks not necessarily orthogonal
- Above illustrates pitfalls

## Discussion

- Why not separate tasks?
- Let population perform search
- Let another mechanism (not population) represent best solution found so far
- Leads us to archive methods

## Archive Methods

- Archives provide a way to
  - collect (according to some organizing principle) “good” individuals over evolutionary time
  - encapsulate wider phenotypic range (than a population contains at any one moment in time)
  - broaden evaluation (and selection pressure) via augmented phenotypic diversity
  - ameliorate evolutionary forgetting
  - represent the result of the evolutionary process

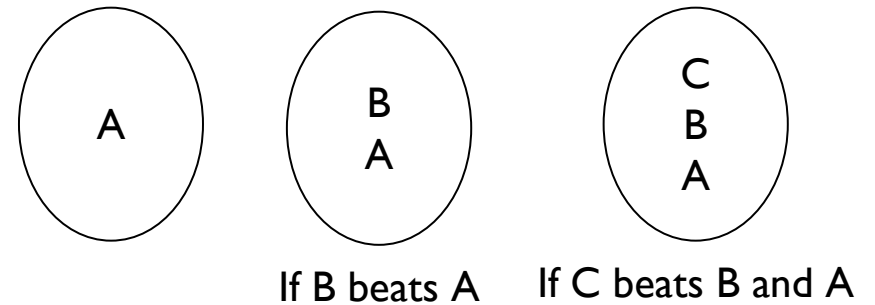
## Archive Methods

- Hall-of-Fame [Rosin & Belew 1997]
  - accumulate fittest of each generation
  - sample  $k$  members for testing current generation
  - shown to help, but weak organizing principle
- Dominance Tournament [Stanley & Miikkulainen 2002]
- Nash memory [Ficici & Pollack 2003]
- Pareto archives [de Jong 2004]

## Dominance Tournament

- ❑ For zero-sum games, symmetric or not
- ❑ Organizing principle is Pareto dominance
- ❑ Add strategy  $X$  to DT archive if and only if  $X$  outperforms each member of archive
- ❑ Each new member inserted into archive has a broader demonstrated range of competence
- ❑ Avoids intransitive cycles
- ❑ Most recently added member is “solution”

## Dominance Tournament

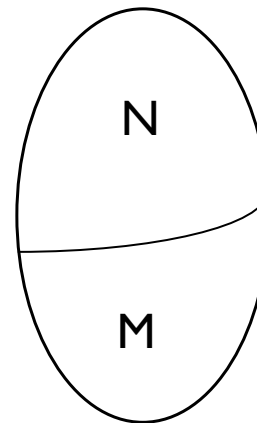


- ❑ If  $D$  beats  $C$ , but not  $B$ , then  $D$  excluded

## Nash Memory

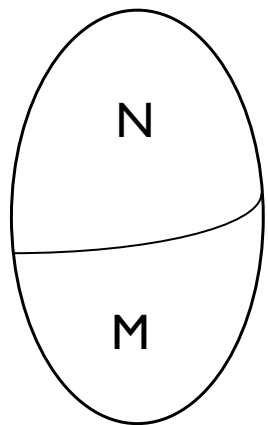
- ❑ For zero-sum games, symmetric or not
- ❑ Organizing principle is Nash equilibrium
- ❑ Begin with arbitrary approximation to Nash equilibrium  $N$  of game, and empty “memory”  $M$
- ❑ If strategy  $S$  beats  $N$ , then update  $N$  and  $M$  to obtain a new Nash approximation that doesn't lose to any strategy in  $S \cup N \cup M$
- ❑ Final approximation  $N$  is “solution”

## Nash Memory



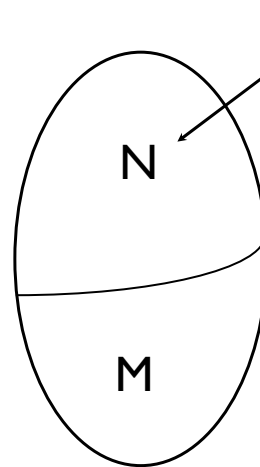
- ❑  $N$  and  $M$  are mutually exclusive sets of pure strategies
- ❑  $N$  is initially an arbitrary pure strategy
- ❑  $M$  is initially the empty set

## Nash Memory



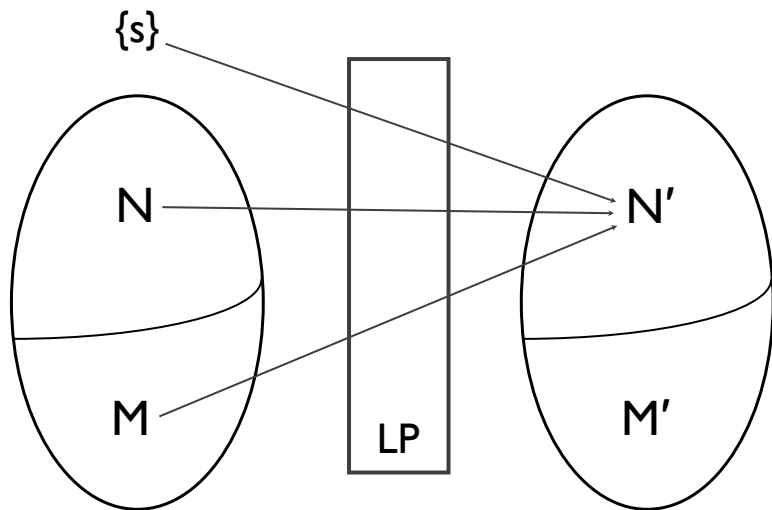
- N is Nash strategy with respect to pure strategies in  $N \cup M$
- M is set of strategies that used to be in N earlier and may be again in the future
- M is of bounded size

## Nash Memory

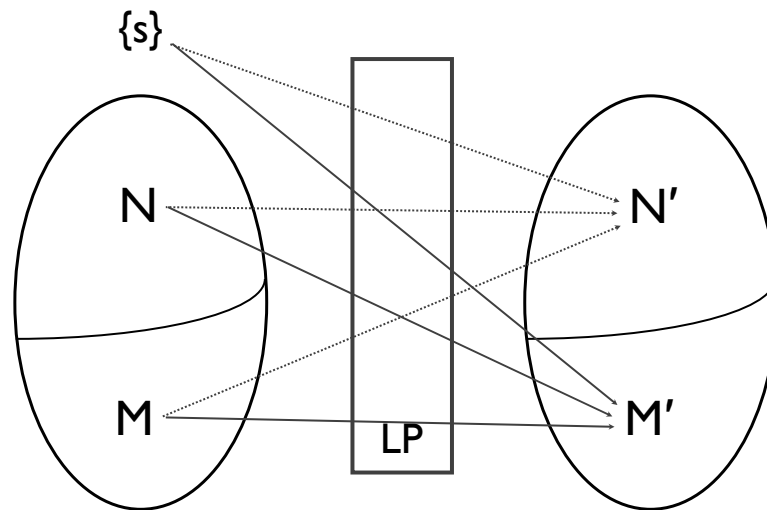


- If  $s$  does not beat N, then discard  $s$ ; keep searching
- Otherwise,  $s$  indicates a weakness in N; update N

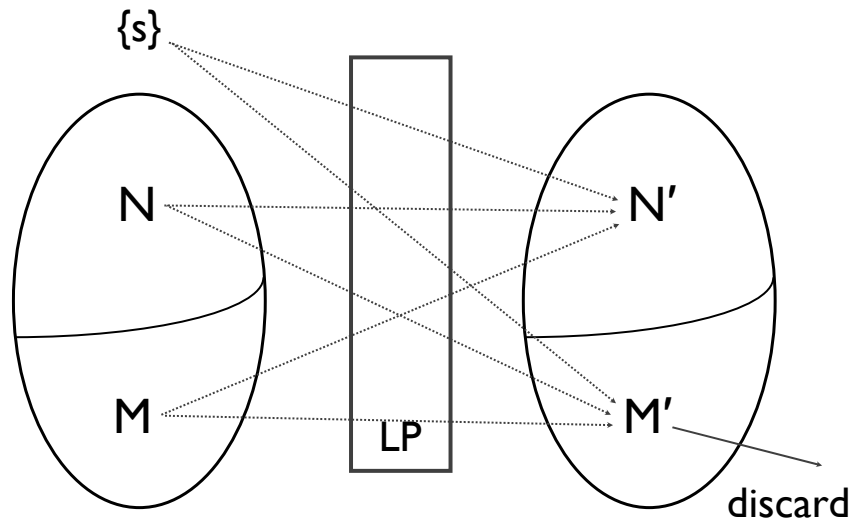
## Nash Memory



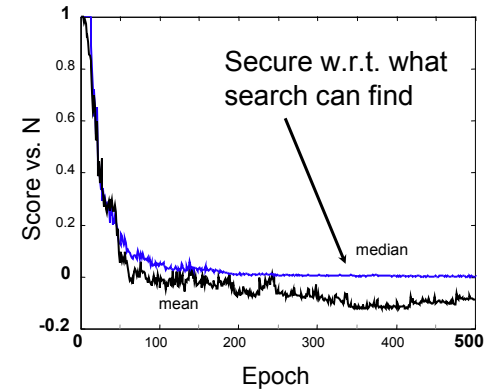
## Nash Memory



## Nash Memory



## Nash Memory

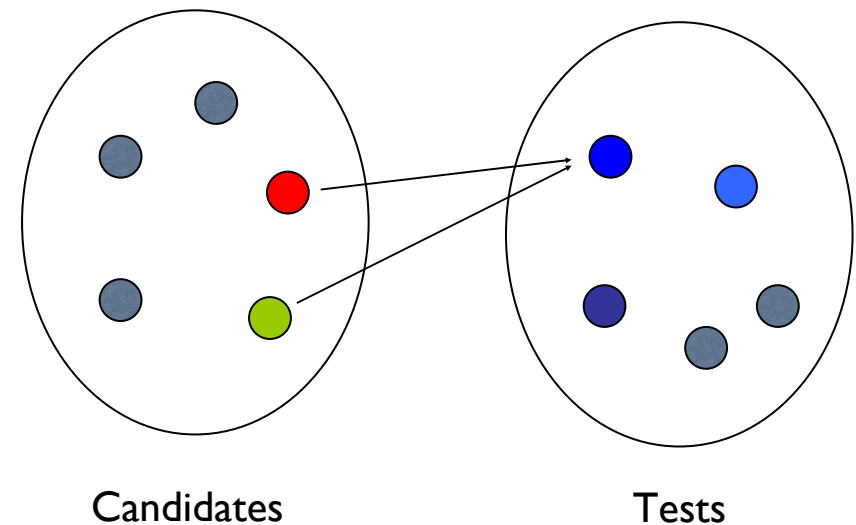


- Even though  $M$  is finite, and strategies discarded, monotonic improvement of  $N$  is approximated

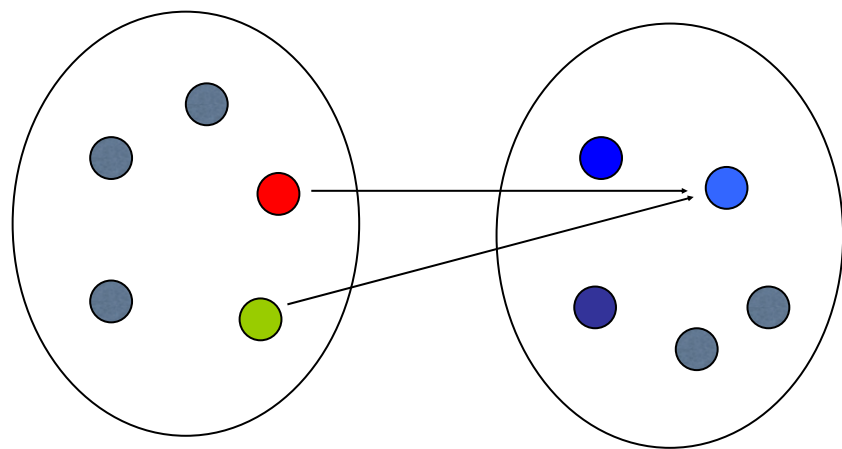
## Pareto Archives

- Pareto Coevolution* [Ficici & Pollack 2001; Noble & Watson 2001] treats entities with two roles: *candidates* and *tests* (sometimes *learners* and *teachers*)
- Candidates** are incented to *perform*
- Tests** are incented to *inform* about candidates
- Key insight: performing  $\neq$  informing

## Performing



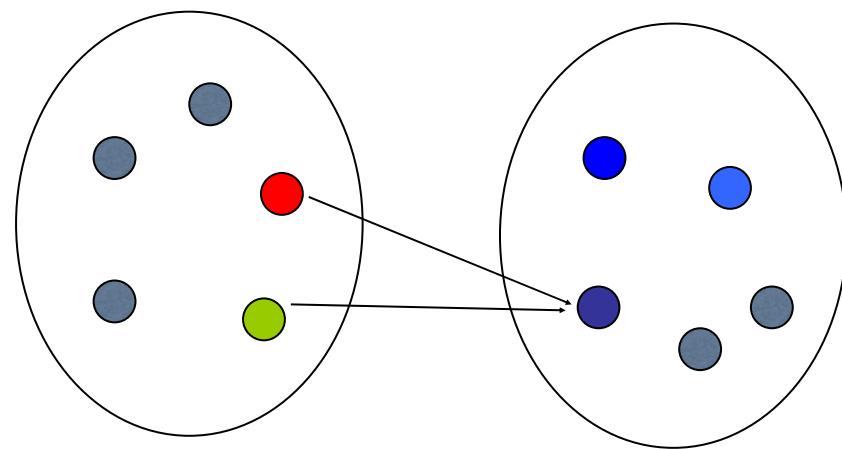
### Performing



Candidates

Tests

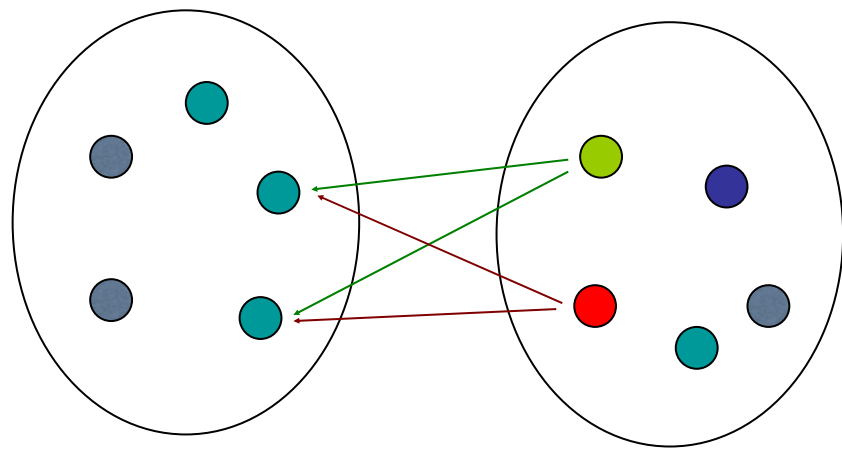
### Performing



Candidates

Tests

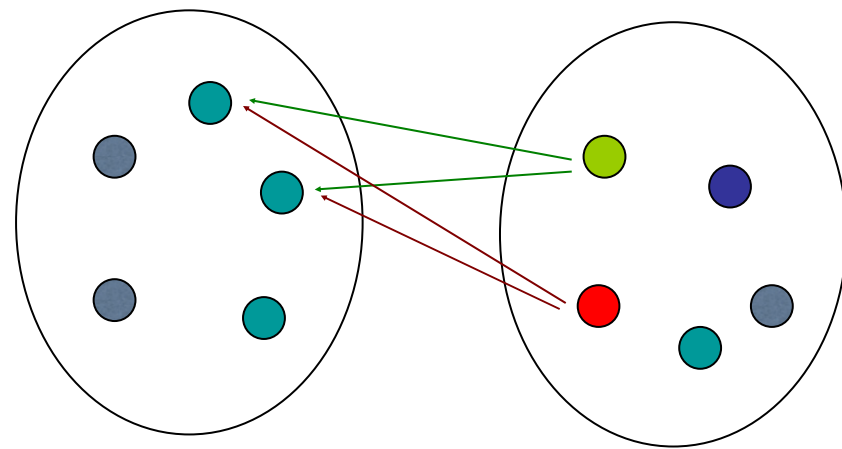
### Informing



Candidates

Tests

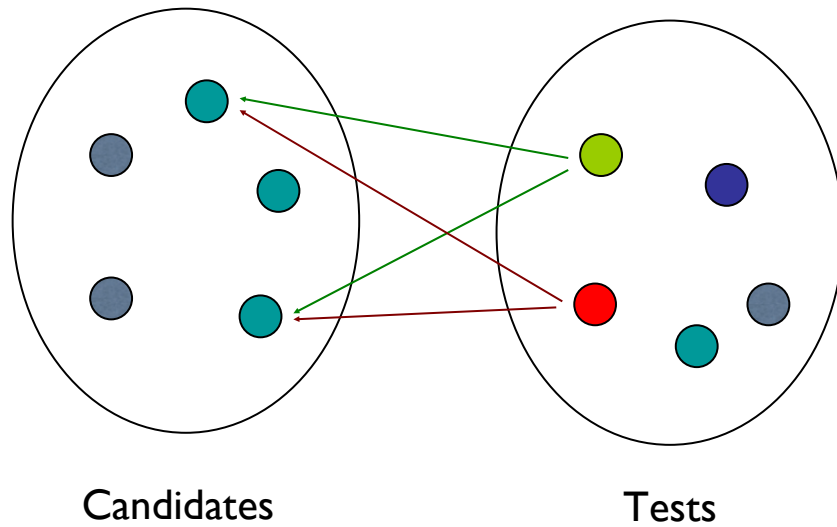
### Informing



Candidates

Tests

## Informing



## Pareto Archives: IPCA

- Incremental Pareto Coevolution Archive [de Jong 2004]
- Theoretically ensures monotonic progress for Pareto Coevolution
- Allows the candidate population to explore
- Test archive maintains candidate distinctions and can grow without bound

## Pareto Archives: LAPCA

- LAYERed Pareto Coevolution Archive [de Jong 2004]
- Keeps a tunable number of Pareto layers
- Approximates IPCA, but bounds the archive – loses monotonicity guarantee
- Combined with NEAT and applied to coevolve Pong players [Monroy et al. 2006]

## Test-Based Problems

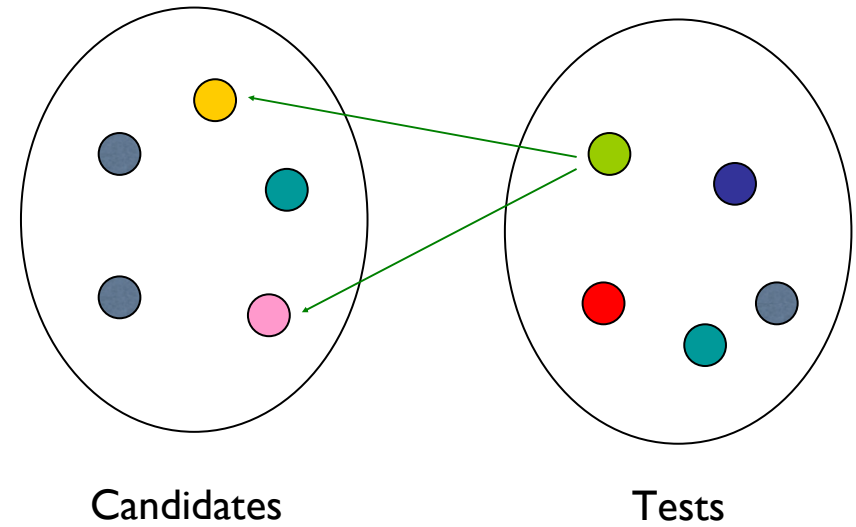
- Candidate solutions are *tested* by interacting with other entities, as in:

<b>Domain</b>	<b>Candidate</b>	<b>Test</b>
Design	Sorting network	Unsorted list
Classification	Classifier	Data point
Function/model regression	Function or model	Input
Strategy learning	First player	Second player

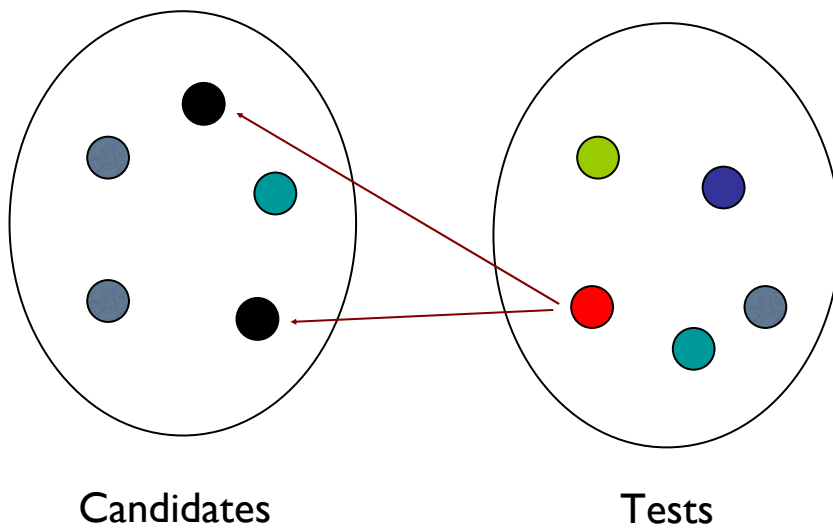
## Pareto Coevolution

- ❑ Maintains two populations, candidate solutions and tests
- ❑ **Candidates** are compared using Pareto dominance:  $A$  dominates  $B$  if it does at least as well as  $B$  against all tests and better on at least one
- ❑ **Tests** are compared using *distinctions* [Ficici & Pollack 2001] or *informativeness* [Bucci & Pollack 2003]
- ❑ Solution set is non-dominated front of candidates and an informative set of tests

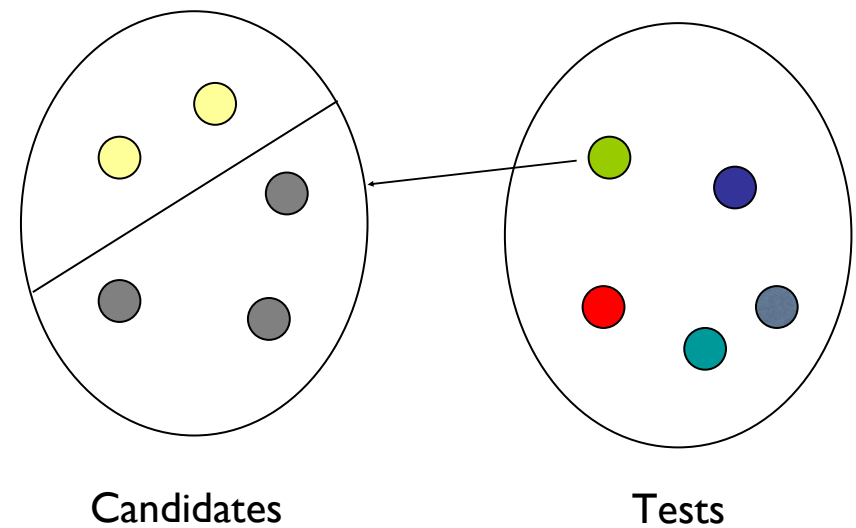
## Shows a Distinction



## Shows No Distinction

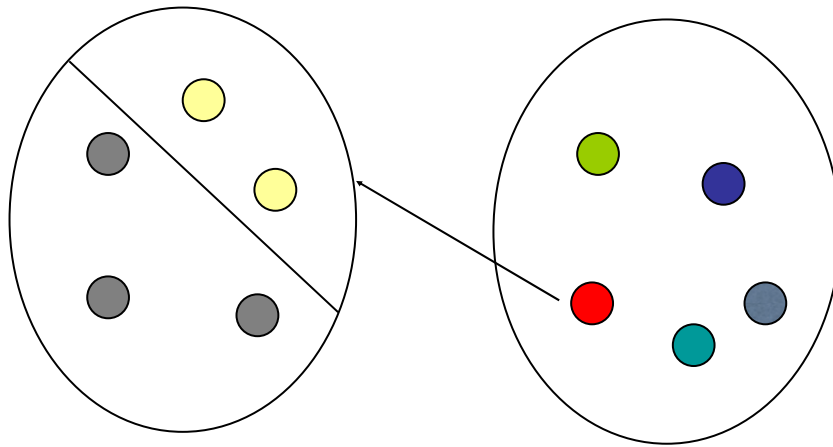


## Informative





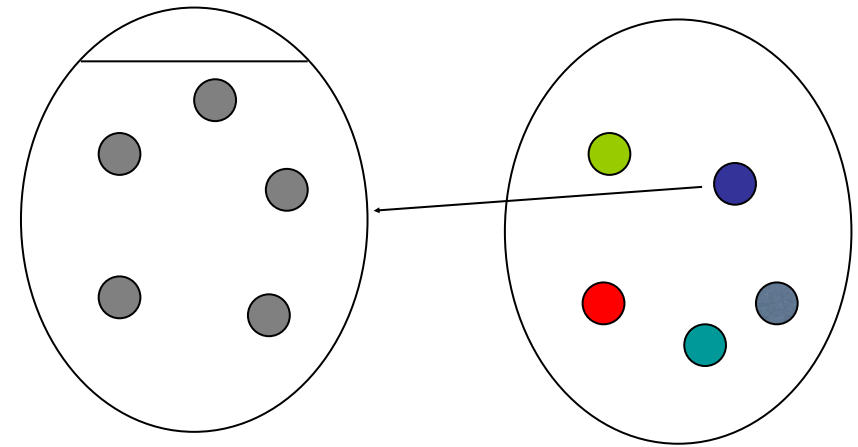
## Differently Informative



Candidates

Tests

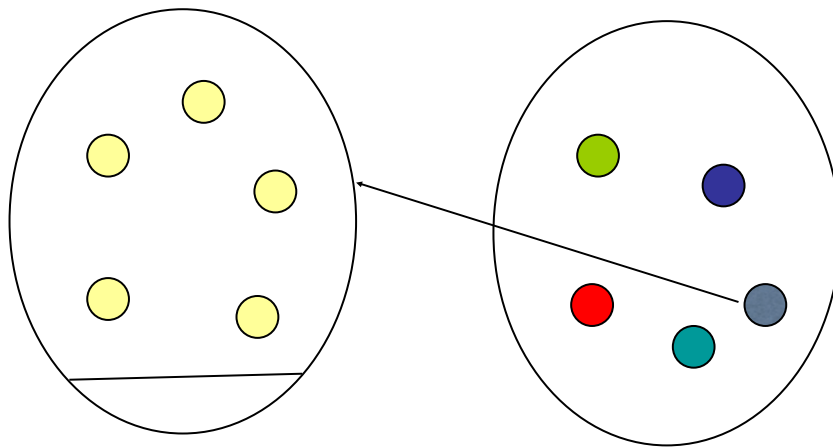
## Uninformative



Candidates

Tests

## Differently Uninformative



Candidates

Tests

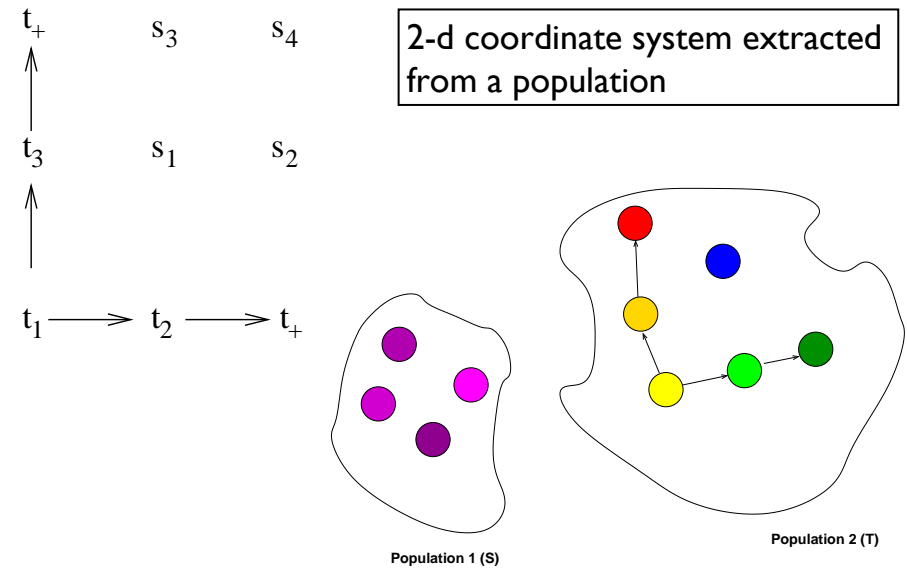
## Reducing the Number of Tests

- Ideal Test Set [Bucci & Pollack 2003]
- Complete Evaluation Set [de Jong & Pollack 2004]
- [de Jong & Pollack 2004] posited the existence of multiple *underlying objectives* akin to fitness functions
- [Bucci et al. 2004] grounded the idea as *coordinate systems (informative dimensions)*

## Dimension Extraction

- Coordinate systems collect several tests into a composite *axis*
- Set of axes forms a coordinate system analogous to a basis for a vector space
- [Bucci et al. 2004] proved coordinate systems exist and gives a polynomial-time algorithm to extract one
- [de Jong & Bucci 2006] gave a CEA, DECA, which extracts coordinate systems from populations to inform selection

## Dimension Extraction



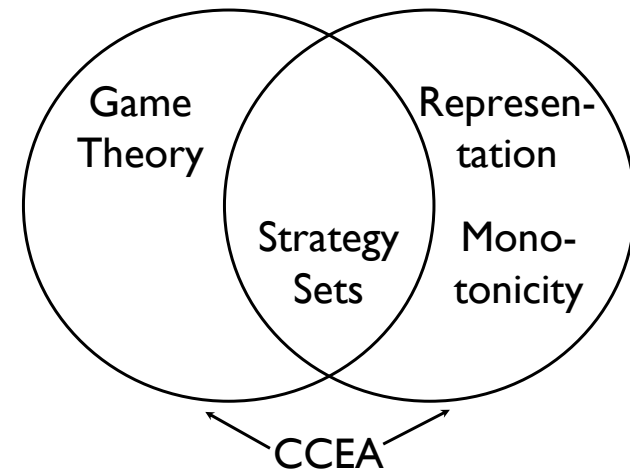
## Reducing the Amount of Testing: EEA

- Estimation-Exploration Algorithm [Lipson et al. 2005]
- Candidates** are models of a system
- Tests** are probes of the real system (assumed to be expensive)
- Aim is to evolve a model of the real system using as few probes as possible

## Main Themes

Interaction

Elaboration



## Cooperative Coevolution

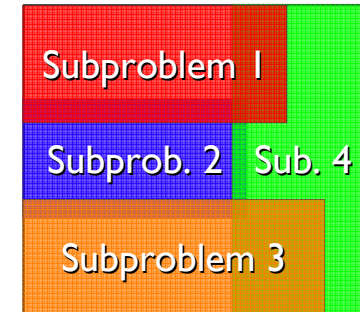
[Potter & De Jong 1994]



- Monolithic problem may be too difficult

## Cooperative Coevolution

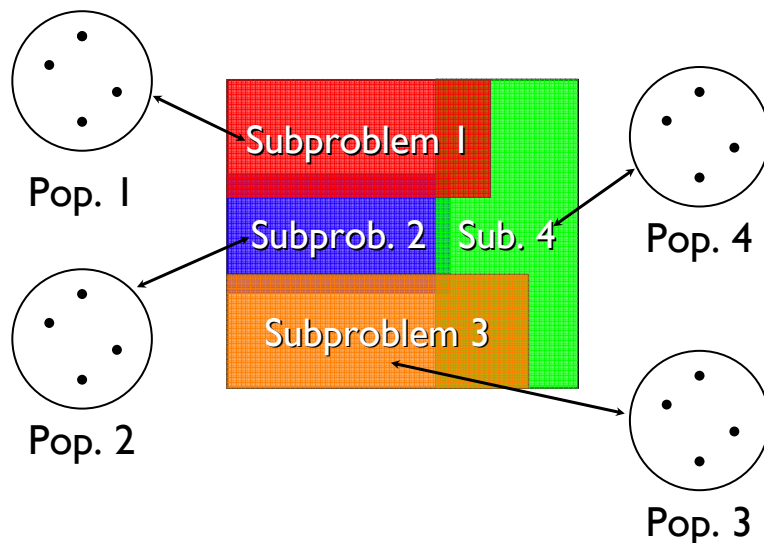
[Potter & De Jong 1994]



- Decompose into mosaic of semi-independent sub-problems

## Cooperative Coevolution

[Potter & De Jong 1994]



## Cooperative Coevolutionary Algorithms (CCEAs)

- [Potter & De Jong 1994] argued that CCEAs optimize functions
- [Wiegand 2003] argued they do not optimize functions, but rather optimize for robustness.
- Used EGT to argue certain Nash equilibria are preferred
- Same work suggested biasing CCEA such that they do optimize

## Biasing CCEA Towards Optimization

- ❑ [Panait et al. 2004] aimed to bias the CCEA by mixing evaluation with another term biasing towards its optimal evaluation
- ❑ [Bucci & Pollack 2005] used Pareto dominance comparison with no bias term; collaborators were tests
- ❑ [Panait et al. 2006] proposed an archive of good collaboration choices, iCCEA

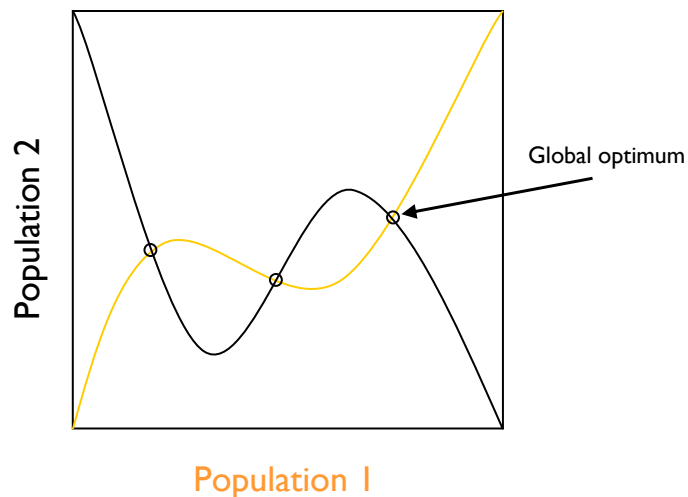
## Analyzing Collaboration Schemes

[Popovici & De Jong 2005]

- ❑ Best response curves are a property of a problem
- ❑ In CCEA, intersection points of best response curves are Nash equilibria
- ❑ Trajectories of individuals is a property of an algorithm; e.g., the collaboration scheme
- ❑ Trajectories which land at best response curve intersection points get stuck even if they are suboptimal

## Analyzing Collaboration Schemes

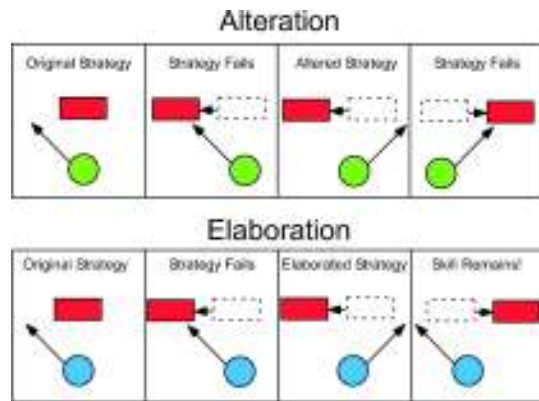
[Popovici & De Jong 2005]



## NeuroEvolution of Augmenting Topologies (NEAT)

- ❑ Evolves increasingly complex neural network topologies [Stanley & Miikkulainen 2004]
- ❑ Mutations occasionally add new structure
- ❑ Speciation protects innovative structures
- ❑ In combination, these mechanisms support elaboration

## Alteration vs. Elaboration



Alteration alone may damage capabilities  
 Elaboration accumulates capabilities  
 Can we abstract this idea?

## Progress in Coevolution

- A core theme in coevolution research:  
How to ensure progress—is it possible?
- Evaluation: individual interacts with others
- Measured quality of an individual is function  
of which other individuals interact with it
- Constantly shifting landscape!
- Open-ended search spaces problematic

## Progress in Coevolution

- Monitoring progress
  - Miller & Cliff 1994
  - Floreano & Nolfi 1997
  - Rosin 1997
  - Stanley & Miikkulainen 2002
  - Bader-Natal & Pollack 2004, 2005

## Approach

- Examine the issue of progress from  
viewpoint of solution concepts
- Some solution concepts intrinsically  
“support” monotonic progress
- Not a value judgment—use whatever  
solution concept is appropriate
- But something to be aware of!

## Desirable Property

- As your knowledge of a search-space increases...
- ... your estimations of a solution should improve

The longer the algorithm runs,  
the better the output should be!

(Experience tells us this is not the case in coev.)

## Desirable Property

- As your knowledge of a  <sup>$\mathcal{P}$</sup>  search-space increases...
- ... your estimations of a solution should improve

## Desirable Property

- As your knowledge of a search-space  <sup>$\mathcal{P}$</sup>  increases...  $\mathcal{W} \subset \mathcal{P}$
- ... your estimations of a solution should improve

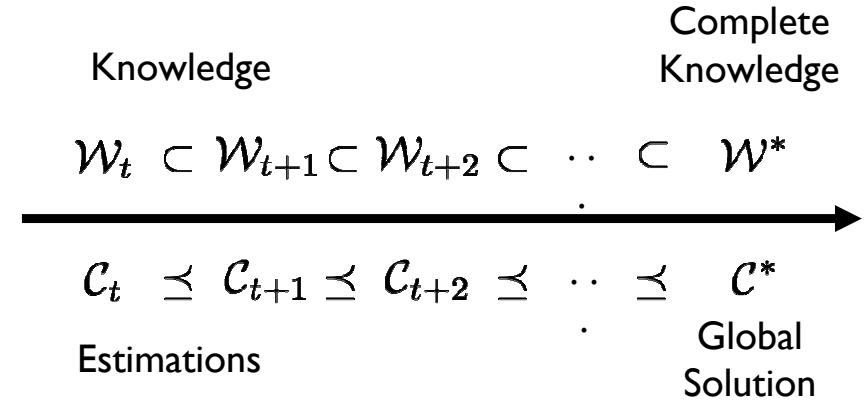
## Desirable Property

- As your knowledge of a search-space  <sup>$\mathcal{P}$</sup>  increases...  $\mathcal{W} \subset \mathcal{P}$
- ... your estimations of a solution should improve  ~~$\mathcal{C} \in \mathcal{R}$~~   
 $\mathcal{C} \in 2^{\mathcal{P}}$

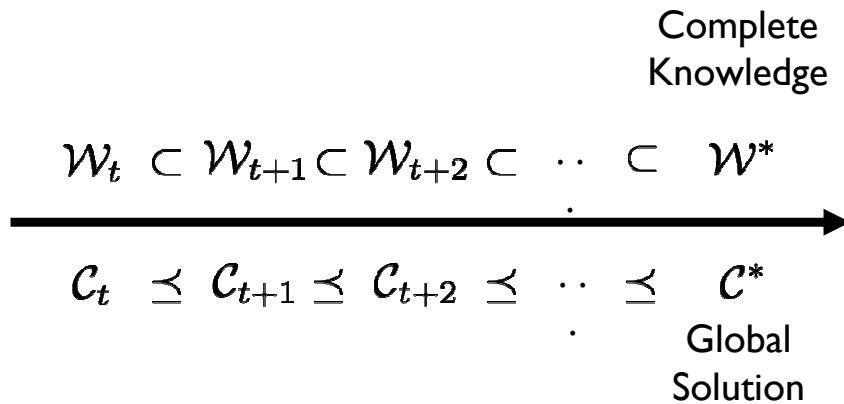
## Desirable Property

- As your knowledge of a search-space increases...  $\mathcal{W} \subset \mathcal{P}$
- ... your estimations of a solution should improve  ~~$\mathcal{C} \in \mathcal{R}$~~   
 $\mathcal{C} \in 2^{\mathcal{P}}$

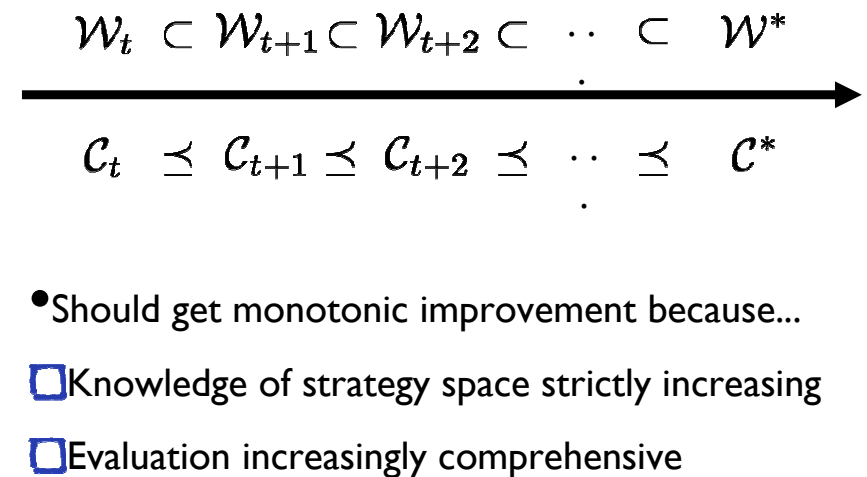
## Monotonic Improvement



## Monotonic Improvement



## Reasoning



## Reasoning

$$\mathcal{W}_t \subset \mathcal{W}_{t+1} \subset \mathcal{W}_{t+2} \subset \dots \subset \mathcal{W}^*$$



$$\mathcal{C}_t \preceq \mathcal{C}_{t+1} \preceq \mathcal{C}_{t+2} \preceq \dots \preceq \mathcal{C}^*$$

- Might not get monotonic improvement because...
- Evaluation never fully complete
- New strategy may radically shift evaluations

## Shift of Perspective

1. Begin with Rock
  2. Discover Paper; Rock loses to Paper
  3. Then discover Scissors; Paper loses, Rock wins
- Paper appears to lose quality; Rock gains it
  - Directional improvement ill-defined concept

## Depends on Solution Concept

$$\mathcal{W}_t \subset \mathcal{W}_{t+1} \subset \mathcal{W}_{t+2} \subset \dots \subset \mathcal{W}^*$$



$$\mathcal{C}_t \preceq \mathcal{C}_{t+1} \preceq \mathcal{C}_{t+2} \preceq \dots \preceq \mathcal{C}^*$$

- If solution concept is “monotonic”...
- then monotonic increase in knowledge  $\Rightarrow$
- monotonic improvement of estimation

## Monotonicity

With a monotonic solution concept...

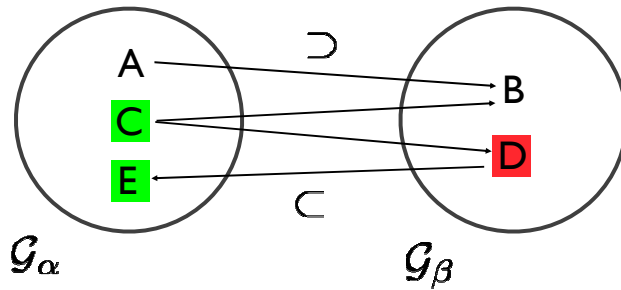
If  $\mathcal{C}_\alpha$  is solution to X and Z, where  $X \supset Z$

Then  $\mathcal{C}_\alpha$  will be a solution to any Y where

$$X \supset Y \supset Z$$



## Monotonicity



$C_\alpha$  solution to games **C** and **E**, where **C**  $\supset$  **E**

$C_\alpha$  not solution to some game **D**, where **C**  $\supset$  **D**  $\supset$  **E**

Then solution concept is non-monotonic

## Monotonicity

- A monotonic solution concept means:
  - once you discard an estimation in favor of another...
  - you will never return to an earlier estimation
  - ... regardless of whatever new strategies you discover in the future
- Non-monotonic solution concept means:
  - you may return to an estimation from some earlier point in time as you discover new strategies

## Monotonic Solution Concepts

- Solution concepts that are monotonic
  - Nash equilibrium
  - Pareto optimality, but only if you exclude newly discovered strategies that appear identical to ones previously discovered
- Non-monotonic
  - Maximal expected payoff; best response
- This notion of monotonicity subsumes that of [de Jong 2005]

# Advanced Tutorial on Coevolution—References<sup>1</sup>

## 1 Background

### 1.1 Game Theory

[Fudenberg and Tirole, 1998], [Nash, 1951]

### 1.2 Dynamical Systems

[Strogatz, 1994]

## 2 Solution Concepts

[Fudenberg and Tirole, 1998], [Ficici, 2004], [de Jong, 2005],  
[Bucci and Pollack, 2007], [Wiegand, 2003]

### 2.1 Solution Concept and Evolutionary Dynamics

[Maynard-Smith and Price, 1973], [Maynard-Smith, 1982],  
[Fogel and Fogel, 1995], [Fogel et al., 1997], [Fogel et al., 1998],  
[Hofbauer and Sigmund, 1998], [Liekens et al., 2004], [Ficici et al., 2005],  
[Ficici, 2006], [Ficici and Pollack, 2007]

## 3 Representation

[Moriarty and Miikkulainen, 1997], [Stanley and Miikkulainen, 2002b],  
[Stanley and Miikkulainen, 2004], [Ashlock et al., 2006]

## 4 Evaluation

[Bull, 2001], [Panait et al., 2004], [Popovici and De Jong, 2005a],  
[Popovici and De Jong, 2005b], [Popovici and De Jong, 2006c],  
[Popovici and De Jong, 2006b], [Popovici and De Jong, 2006a]

### 4.1 Test-Based Evaluation

[Juillé and Pollack, 1996b], [Juillé and Pollack, 1996a],  
[Juillé and Pollack, 1998], [Juillé, 1999], [Juillé and Pollack, 2000],  
[Watson and Pollack, 2000], [Ficici and Pollack, 2001],  
[Ashlock et al., 2004], [Bucci and Pollack, 2002], [Bucci and Pollack, 2003],  
[de Jong and Pollack, 2003], [Bucci et al., 2004], [de Jong, 2004a],  
[de Jong, 2004b], [Bongard and Lipson, 2005], [de Jong and Bucci, 2006]

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## 5 Pareto Coevolution

[Watson and Pollack, 2000], [Ficici and Pollack, 2001],  
[Noble and Watson, 2001], [Bucci and Pollack, 2002],  
[Bucci and Pollack, 2003], [de Jong and Pollack, 2003], [Bucci et al., 2004],  
[de Jong, 2004a], [de Jong, 2004b], [Bongard and Lipson, 2005],  
[de Jong and Bucci, 2006], [Watson, 2006]

## 6 Archive Methods, design and use

[Rosin and Belew, 1997], [Stanley and Miikkulainen, 2002a],  
[Ficici and Pollack, 2003], [de Jong, 2004a], [de Jong, 2004b],  
[Monroy et al., 2006]

## 7 Progress in Coevolution

[Miller and Cliff, 1994], [Floreano and Nolfi, 1997],  
[Bader-Natal and Pollack, 2004], [de Jong, 2005],  
[Bader-Natal and Pollack, 2005], [Ficici, 2005]

## 8 Cooperative Coevolution

[Potter and Jong, 1994], [Potter and Jong, 2000], [Wiegand et al., 2001],  
[Wiegand et al., 2002b], [Wiegand et al., 2002a], [Wiegand et al., 2003],  
[Wiegand, 2003], [Jansen and Wiegand, 2004], [Panait et al., 2004],  
[Bucci and Pollack, 2005], [Popovici and De Jong, 2005a],  
[Popovici and De Jong, 2005b], [Popovici and De Jong, 2006c],  
[Popovici and De Jong, 2006b], [Popovici and De Jong, 2006a]

## 9 Markov Analyses

[Bull, 2001], [Schmitt, 2003a], [Schmitt, 2003b]

## 10 No Free Lunch

[Wolpert and Macready, 1997], [Wolpert and Macready, 2005]

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